Vector V102 GPS Compass Series

General Navigation Heading and Positioning Smart Antenna



- Provides heading, positioning, heave, roll and pitch
- Excellent in-band and out-of-band interference rejection
- 0.75 degree heading accuracy in amazingly small form factor
- · Extremely quick time-to-first-fix
- Differential positioning accuracy of 1.0 m, 95% of the time

- Integrated gyro and tilt sensors deliver fast startup times and provide heading updates during temporary loss of GPS
- SBAS compatible (WAAS, EGNOS, MSAS, etc.) and optional external differential input
- COAST™ technology maintains differentially corrected positioning for 40 minutes after loss of differential signal

Experience superior navigation from the accurate heading and positioning performance available with the Vector™V102™ GPS compass. The Vector V102 uses SBAS (WAAS, EGNOS, MSAS, etc.) for differential GPS positioning allowing Hemisphere GNSS to provide a low cost and highly effective heading and position based smart antenna.

The rugged and low profile enclosure combines Hemisphere GPS' Crescent® Vector II OEM technology and two multipathresistant antennas for accuracy, portability and simple installation. The smart antenna - measuring less than half-meter length - mounts easily to a flat surface or pole. The stability and maintenance-free design of the Vector V102 provides traditional GPS positioning and heading at a low cost.





GPS Sensor Specifications

Receiver Type:

L1 C/A code, with carrier phase smoothing
Channels:

Two 12-channel, parallel tracking (Two
10-channel when tracking SBAS)

2-channel, parallel tracking

Update Rate: 10 Hz standard, 20 Hz optional (position and

heading)

Horizontal Accuracy: < 1.0 m 95% confidence (DGPS1)

< 2.5 m 95% confidence (autonomous, no

SA2)

Heading Accuracy: < 0.75° rms

Pitch/Roll Accuracy: < 1.5° rms

Heave Accuracy: < 30 cm⁵ rms

Rate of Turn: 90°/s maximum

Compass Safe

SBAS Tracking:

Distance: 30 cm⁴

Cold Start: < 60 s (no almanac or RTC)
Warm Start: < 20 s typical (almanac and RTC)

Hot Start: < 1 s typical (almanac, RTC and position)

Heading Fix: < 10 s typical (valid position)

Maximum Speed: 1,850 mph (999 kts)
Maximum Altitude: 18,288 m (60,000 ft)

Communications

Serial Ports: 2 full-duplex RS-232
Baud Rates: 4800 - 115200
Correction I/O Protocol: RTCM SC-104

Data I/O Protocol: NMEA 0183, NMEA 2000, Crescent binary³,

CAN

Environmental

Operating Temperature: -30°C to $+70^{\circ}\text{C}$ (-22°F to $+158^{\circ}\text{F}$) Storage Temperature: -40°C to $+85^{\circ}\text{C}$ (-40°F to $+185^{\circ}\text{F}$)

Humidity: 100% non-condensing

Vibration: IEC 60945

EMC: FCC Part 15, Subpart B

CISPR22

IEC 60945 (CE)

Power

Input Voltage: 6 to 36 VDC

Power Consumption: ~ 3 W nominal

Current Consumption: 240 mA @ 12 VDC

Power Isolation: Isolated to enclosure

Reverse Polarity Protection: Yes

Mechanical

Enclosure: UV resistant, white plastic, AES HW

600G, non-corrosive, self-extinguishing

Dimensions: 41.7 L x 15.8 W x 6.9 H (cm)

16.4 L x 6.2 W x 2.7 H (in)

Weight: ~1.5kg (3.3 lb)
Power/Data Connector: 12-pin, Female, IP67

Aiding Devices

Gyro: Provides smooth heading, fast heading

reacquisition and reliable < 1° heading for periods up to 3 minutes when loss

of GPS has occurred

Tilt Sensors: Assists in fast start-up of heading

solution

Authorized Distributor:

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¹ Depends on multipath environment, number of satellites in view, satellite geometry, ionospheric activity and use of SBAS

² Depends on multipath environment, number of satellites in view, satellite geometry and ionospheric activity

³ Hemisphere GNSS proprietary

⁴ This is the minimum safe distance measured when the product is placed in the vicinity of the steering magnetic compass. The ISO 694 defines "vicinity" relative to the compass as within 5 m (16.4 ft) separation

 $^{^{\}it 5}$ Based on a 40 second time constant