

Eclipse[™] Vector[™] H328 GNSS OEM Board





Patlas[®]

Develop sophisticated machine control and navigation solutions in a complex world full of dynamic environments. The Vector H328 is our most advanced GNSS heading and positioning board.

The Vector H328 uses dual antenna ports to create a series of additional capabilities to Eclipse Vector technology including fast, high-accuracy heading over short baselines, RTK positioning, onboard Atlas L-band, RTK-enabled heave, low-power consumption, and precise timing.

Scalable Solutions

With the Vector H328, positioning is scalable and field upgradeable with all Hemisphere software and service options. Use the same centimeter-level accuracy in either single frequency mode, or employ the full performance and fast RTK initialization times over long distances with multi-frequency multi-constellation GNSS signals. High-accuracy L-band positioning from meter to sub-decimeter levels are available via Atlas correction service.

Ease of Migration

Leverage the industry standard form factor for easy upgradeability from other manufacturers' modules.

Key Features

- Extremely accurate heading with long baselines
- Multi-frequency position, dual-frequency heading supporting GPS, GLONASS, BeiDou, Galileo, QZSS, IRNSS, and L-band
- Atlas® L-band capable to 4 cm RMS
- Athena™ GNSS engine providing best-in-class RTK performance
- Excellent coasting performance
- 5 cm RMS RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection
- New multi-axis gyro and tilt sensor for reliable coverage during short GNSS outages

GNSS Receiver Specifications

Receiver Type: Multi-Frequency GPS, GLONASS,

BeiDou, Galileo, QZSS, and Atlas GPS L1CA/L1P/L1C/L2P/L2C/L5 Signals Received:

GLONASS G1/G2, P1/P2 BeiDou B1/B2/B3

GALILEO E1BC/E5a/E5b QZSS L1CA/L2C/L5/L1C

Atlas 1059

Channels: **GPS Sensitivity:** -142 dBm

SBAS Tracking: 3-channel, parallel tracking **Update Rate:** 10 Hz standard, 1 Hz or 20 Hz optional (with activation)

Timing (1 PPS)

Accuracy: 20 ns

Rate of Turn: 100°/s maximum

Cold Start: 60 s typical (no almanac or RTC) 30 s typical (almanac and RTC) Warm Start: **Hot Start:** 10 s typical (almanac, RTC and

position)

Heading Fix: 10 s typical (Hot Start)

Antenna Input

Impedance: 50 Ω

Maximum Speed: 1,850 mph (999 kts) Maximum Altitude: 18,288 m (60,000 ft)

Accuracy

Positioning: RMS (67%) 2DRMS (95%) 1.2 m $2.5 \, \mathrm{m}$

Autonomous, no SA: 1 0.6 m SBAS: 1 $0.3 \, \mathrm{m}$ Atlas H10: 1, 3 $0.08 \, \text{m}$ $0.04 \, \text{m}$ Atlas H30: 1, 3 $0.15 \, \text{m}$ $0.3 \, \mathrm{m}$ Atlas Basic: 1,3 1.0 m $0.50 \, \text{m}$

RTK: 1 8 mm + 1 ppm 15 mm + 2 ppm

Heading (RMS): 0.16° rms @ 0.5 m antenna

separation

0.08° rms @ 1.0 m antenna

separation

0.04° rms @ 2.0 m antenna

separation

0.02° rms @ 5.0 m antenna

separation

Pitch/Roll (RMS): 10

30 cm rms (DGNSS), 5 cm rms (RTK) Heave (RMS): 1

L-Band Receiver Specifications

Receiver Type: Single Channel Channels: 1525 to 1560 MHz

Sensitivity: -130 dBm **Channel Spacing:** 5.0 kHz

Satellite Selection: Manual and Automatic **Reacquisition Time:** 15 seconds (typical)

Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity

Depends on multipath environment, number of satellites in view, SBAS coverage, satellite geometry, and ionospheric activity

Hemisphere GNSS proprietary

With future firmware upgrade and activation

CMR and CMR+ do not cover proprietary messages outside of the typical standard



Communications

3 x full-duplex (1 x 3.3V CMOS, 1 x 3.3V CMOS with flow control, 1 x RS-232 with flow

control)

1 x USB Device

1 x Ethernet 10/100Mbps

2 x CAN (NMEA2000, ISO 11783)

1 x SPI 3.3V CMOS

Interface Level: 4800 - 115200 **Baud Rates:**

Correction I/O Protocol: Hemisphere GNSS proprietary ROX

format, RTCM v2.3, RTCM v3.2,

CMR⁵, CMR+⁵ NMEA 0183, Crescent binary ⁵ 1 PPS, CMOS, active high, rising Data I/O Protocol: **Timing Output:** edge sync, $10 \text{ k}\Omega$, 10 pF load

CMOS, active low, falling edge

sync, $10 \text{ k}\Omega$, 10 pF load

Power

Input Voltage: 3.3 VDC +/- 5%

Power Consumption:

Yes

2.0 W nominal GPS (L1) 2.7 W nominal GPS (L1/L2) and

GLONASS (G1/G2)

3.8 W nominal All Signals + L-band 0.61 A nominal GPS (L1) 0.82 A nominal GPS (L1/L2)

Current Consumption:

1.15 A nominal All Signals + L-band

5 VDC maximum

Antenna Voltage: Antenna Short Circuit **Protection:**

Event Marker Input:

Antenna Gain Input Range:

10 to 40 dB

Environmental

Operating Temperature:

Storage Temperature:

Humidity:

 -40° C to +85°C (-40°F to +185°F -40°C to +85°C (-40°F to +185°F) 95% non-condensing (when in an

enclosure)

Mechanical Shock: EP455 Section 5.14.1

Operational (when mounted in an enclosure with screw mounting

holes utilized)

Vibration: EP455 Section 5.15.1 Random CE (IEC 60945 Emissions and EMC:

Immunity) FCC Part 15, Subpart B

CISPR 22

Mechanical

100 L x 60 W x 10 H (mm) 3.9 L x 2.4 W x 0.4 (in) 44 g (1.56 oz) **Dimensions:**

Weight:

Status Indications (LED): Power, Primary and Secondary GNSS lock, Differential lock, DGNSS

position, Heading

Power/Data

24-pin male header 2 mm pitch 16-pin male header 2 mm pitch Connector:

Antenna Connectors: MMCX, female, straight

Aiding Devices

Gyro:

Provides smooth and fast heading reacquisition. During loss of GNSS signals heading stability is degraded by < 1° per minute for up to 3

minutes.

Provide pitch, roll data and assist in Tilt Sensors:

fast start-up and reacquisition of

heading solution

Hemisphere GNSS

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